

# White-Box Testing

# White-Box Testing

- ❑ White-box testing (testing) is based on knowledge of the **internal logic** of an **application's code**.
- ❑ It determines whether the **program-code structure** and **logic** is faulty.
- ❑ White-box test **cases are accurate** only if the tester knows **what the program is supposed to do**.

# Most Significant White-Box Techniques

- Code coverage
- Fault injection
- Mutation testing

# Code Coverage

❑ Code coverage defines **the degree of source code** which has been tested

❑ There are several criteria for the code coverage:

**Statement coverage:** The line of code coverage granularity.

**Decision (branch) coverage:** Control structure (for example, if-else) coverage granularity.

**Condition coverage:** Boolean expression (true-false) coverage granularity.

**Paths coverage:** Every possible route coverage granularity.

**Function coverage:** Program functions coverage granularity.

**Entry/exit coverage:** Call and return of the coverage granularity.

# Statement Coverage

$$\text{Statement Coverage} = \frac{\text{Number of executed statements}}{\text{Total number of statements}} \times 100$$

# Decision Coverage

$$\text{Decision coverage} = \frac{\text{Number of decision outcomes exercised}}{\text{Total number of decision outcomes}} \times 100\%$$

# Fault Injection

- ❑ Fault injection is the process of **injecting faults** into software to determine how well (or badly) some SUT (System Under Test) behaves.
  - ❑ Defects can be said to propagate AND
  - ❑ The effects of defects are visible in program states
    - ❖ an error exists
    - ❖ a fault becomes a failure.
- Briefly;
- ❑ In software testing, fault injection is a technique for improving the coverage of a test by **introducing faults to test code paths**

# System Under Test

- ❑ SUT is executed with specific input values to find failures in its behavior.
- ❑ The actual SUT should ensure that the design and code, environment (libraries, operating system and network support, and so on) are correct



# Fault Injection Methods

## Compile-Time Injections

- ❑ It is a fault injection technique where source code is modified to inject simulated faults into a system.

## Run-Time Injections

- ❑ It makes use of software trigger to inject a fault into a software system during run time.
- ❑ The Trigger can be of two types
  - ❖ Time Based triggers
  - ❖ Interrupt Based Trigger

# Mutation Testing

- ❑ Mutation testing validates tests and their data by running them against many copies of the SUT containing different, single, and deliberately inserted changes.
- ❑ Mutation testing helps to identify omissions in the code.

## Value Mutation

```
public int Segment(int t[], int l, int u){
    // Assumes t is in ascending order, and l<u,
    // counts the length of the segment
    // of t with each element l<t[i]<u
    int k = 0;
    for(int i=0; i<t.length && t[i]<u; i++){
        if(t[i]>l){
            k++;
        }
    }
    return(k);
}
```

Mutating to k=1 causes miscounting

Here we might mutate the code to read `i=1`, a test that would kill this would have `t` length 1 and have `l < t[0] < u`, then the program would fail to count `t[0]` and return 0 rather than 1 as a result

## Statement Mutation

```
public int Segment(int t[], int l, int u){  
    // Assumes t is in ascending order, and l<u,  
    // counts the length of the segment  
    // of t with each element l<t[i]<u  
    int k = 0;  
  
    for(int i=0; i<t.length && t[i]<u; i++){  
        if(t[i]>l){  
            k++;  
        }  
    }  
    return(k);  
}
```

Here we might consider deleting this statement (then count would be zero for all inputs, we might also duplicate this line in which case all counts would be doubled.

## Decision Mutation

```
public int Segment(int t[], int l, int u){  
    // Assumes t is in ascending order, and l<u,  
    // counts the length of the segment  
    // of t with each element l<t[i]<u  
    int k = 0;  
    for(int i=0; i<t.length && t[i]<u; i++){  
        if(t[i]>l){  
            k++;  
        }  
    }  
    return(k);  
}
```

Mutating to  $t[i]>u$  will cause miscounting

We can model “one-off” errors in the loop bound by changing this condition to  $i \leq t.length$  - provided array bounds are checked exactly this will provoke an error on every execution.

# Coverage Criteria

Graph Coverage

Logic Coverage

# Coverage Criteria

- ❑ A coverage criterion is simply a recipe for generating **test requirements (TR)** in a systematic way.

In other words:

- ❑ A coverage criterion is a rule or collection of rules that impose test requirements (TR) on a test set.

# Graph Coverage Criteria

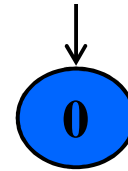
- ❑ **Structural Coverage Criteria** : Defined on a graph just in terms of **nodes and edges**
- ❑ **Data Flow Coverage Criteria** : Requires a graph to be annotated with references to variables



# Graph and Test Paths

- ❑ A set  $N$  of nodes,  $N$  is **not empty**
- ❑ A set  $N_0$  of initial nodes,  $N_0$  is not empty
- ❑ A set  $N_f$  of final nodes,  $N_f$  is not empty
- ❑ A set  $E$  of edges, each edge from one node to another
- ❑ Test Path : A path that **starts** at an **initial node** and **ends** at a **final node**
  - ❖ Test paths represent execution of test cases
    - ✓ Some test paths can be executed by many tests
    - ✓ Some test paths cannot be executed by any tests

# Node Coverage

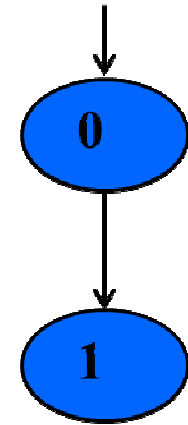


- ❑ A graph with **only one node** will not have any edges
- ❑ **Node Coverage** : TR contains each reachable node in G
- ❑ The length of Node Coverage is 0

In other words:

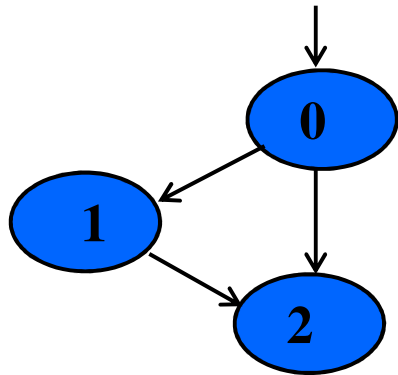
- ❑ **Node Coverage**: Test set satisfies node coverage on graph iff for every syntactically **reachable node n** in set N

# Edge Coverage



- ❑ Edge coverage is **slightly stronger** than **node coverage**
- ❑ Edge coverage needs to **require Node Coverage** on the graph
- BUT
- ❑ Edge Coverage will **not subsume Node Coverage**
- ❑ So we define **“length up to 1”** instead of simply **“length 1”**
  - ❖ The **“length up to 1”** allows for graphs with one node and no edges

# Structural Coverage Example -1



Node Coverage (NC) : TR = { 0, 1, 2 }

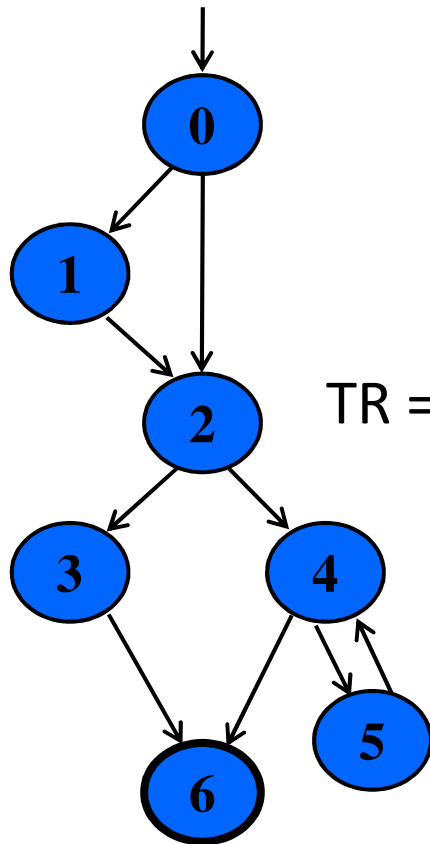
Test Path = [ 0, 1, 2 ]

Edge Coverage(EC) : TR = { (0,1), (0, 2), (1, 2) }

Test Paths = [ 0, 1, 2 ] [ 0, 2 ]

- NC and EC are only different when there is an edge and another subpath between a pair of nodes (as in an “if-else” statement)

# Structural Coverage Example -2



## Node Coverage

TR = { 0, 1, 2, 3, 4, 5, 6 }

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 1, 2, 4, 5, 4, 6 ]

## Edge Coverage

TR = { (0,1), (0,2), (1,2), (2,3), (2,4), (3,6), (4,5), (4,6), (5,4) }

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 2, 4, 5, 4, 6 ]

path (t<sub>1</sub>) = [ 0, 1, 2, 3, 6 ]

path (t<sub>2</sub>) = [ 0, 2, 4, 5, 4, 6 ]

T = { t<sub>1</sub>, t<sub>2</sub> }